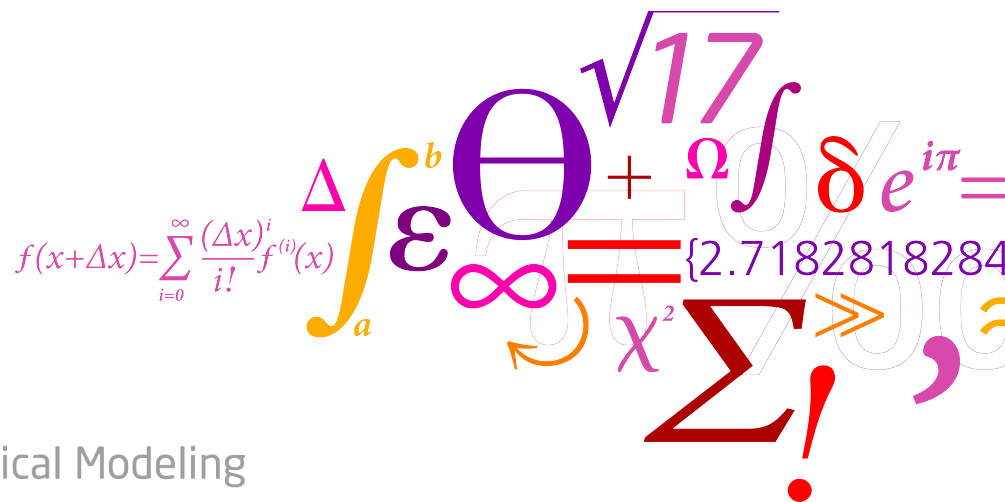


Infinite non-negative matrix factorization

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$$f(x+\Delta x) = \sum_{i=0}^{\infty} \frac{(\Delta x)^i}{i!} f^{(i)}(x)$$

The image contains a collage of mathematical symbols and formulas. The most prominent is the Taylor series expansion of a function $f(x+\Delta x)$. Other symbols include the Greek letter ϵ , the Greek letter θ , the Greek letter Ω , the Greek letter δ , the Greek letter χ , the Greek letter σ , the Greek letter π , the Greek letter ∞ , the Greek letter $\sqrt{17}$, the Greek letter Δ , the Greek letter \int , the Greek letter \sum , the Greek letter \gg , and the Greek letter $!$.

Infinite non-negative matrix factorization

Non-negative matrix factorization (NMF)

- Matrix factorization
 - Algorithms in multivariate analysis / linear algebra
 - Matrix is factored into the product of two matrices
 - Assumptions about the factors lead to different algorithms
 - PCA, FA, ICA, NMF, VQ, etc.

$$\mathbf{V} = \mathbf{W} \mathbf{H} + \mathbf{E}$$

$I \times J$ $I \times D$ $D \times J$ $I \times J$

- NMF: Factors constrained to be non-negative

$$\text{s.t. } \mathbf{W}, \mathbf{H} \geq \mathbf{0}$$

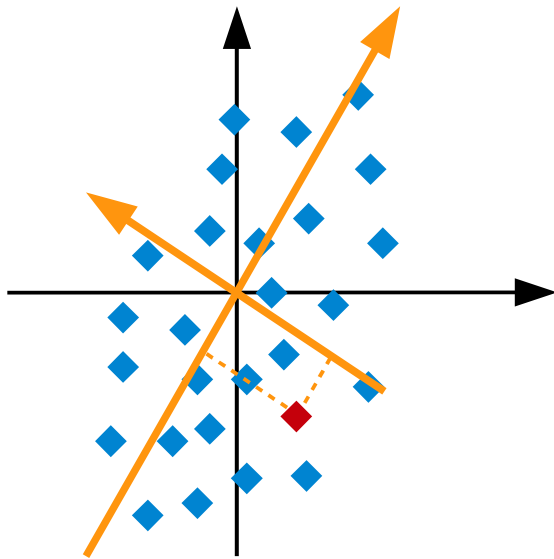
- Problem: Efficient model order selection

Infinite non-negative matrix factorization

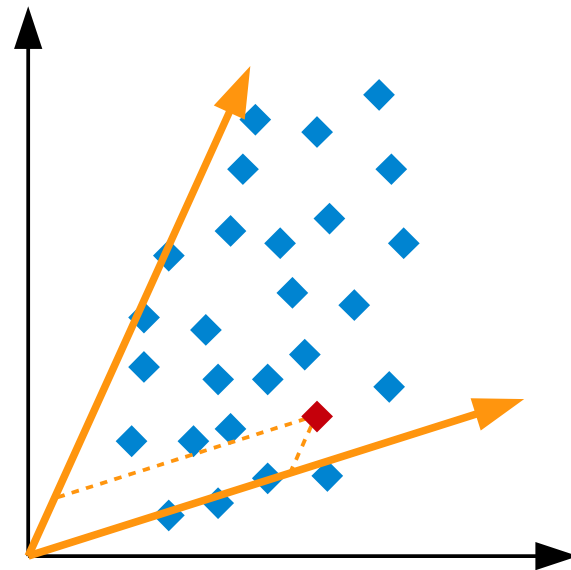
Non-negative matrix factorization (NMF)

$$\underset{I \times J}{V} = \underset{I \times D}{W} \underset{D \times J}{H} + \underset{I \times J}{E}$$

Principal component analysis



Non-negative matrix factorization



Infinite non-negative matrix factorization

Non-negative matrix factorization (NMF)

$$\underset{I \times J}{V} = \underset{I \times D}{W} \underset{D \times J}{H} + \underset{I \times J}{E} \quad \text{s.t. } W, H \geq 0$$

Applications of NMF

- Document clustering and topic discovery
 - Word occurrence counts
- Learning image basis functions
 - Pixel intensities
- Unmixing spectral data (hyperspectral imaging, chemometrics, etc.)
 - Spectral amplitudes

Infinite non-negative matrix factorization

Bayesian NMF

$$\underset{I \times J}{\mathbf{V}} = \underset{I \times D}{\mathbf{W}} \underset{D \times J}{\mathbf{H}} + \underset{I \times J}{\mathbf{E}} \quad \text{s.t. } \mathbf{W}, \mathbf{H} \geq \mathbf{0}$$

- Principled framework
 - Data and parameters modeled as stochastic variables
 - Models uncertainty about the factors
 - All assumptions are made explicit
- Many extensions are special cases
- Gives predictions with error-bars (credible intervals)
- **Model selection is integrated in the framework**

Infinite non-negative matrix factorization

Choosing the number of factors

Resampling

- Crossvalidation, Bootstrapping, etc.

Asymptotic theory

- Bayesian information criterion (BIC), etc.

Bayesian model comparison

- Chib's method, Thermodynamic integration, etc.

Formulating a super-model

- **A comprehensive model that comprises factorizations of any order**
- **Model selection is integrated in the inference procedure**

Infinite non-negative matrix factorization

Related infinite matrix factorization methods

- Based on the Indian buffet process
(Griffiths and Ghahramani, 2006)
 - Infinite binary matrix factorization
(Meeds et al. 2007)
 - Infinite sparse coding, Infinite independent component analysis
(Knowles and Ghahramani, 2007)

$$V = A(S \odot Z) + E$$

↑ Unbounded binary matrix

- Our approach
 - Not Indian buffet process
 - Reversible jump Markov chain Monte Carlo (RJMCMC)
(Green, 1995)

Infinite non-negative matrix factorization

Infinite NMF

$$\underbrace{p(\mathbf{W}, \mathbf{H}, D | \mathbf{V})}_{\text{Posterior}} \propto \underbrace{p(\mathbf{V} | \mathbf{W}, \mathbf{H}, D)}_{\text{Likelihood}} \underbrace{p(\mathbf{W} | D)}_{\text{Priors}} \underbrace{p(\mathbf{H} | D)}_{\text{Priors}} \underbrace{p(D)}_{\text{Priors}}$$

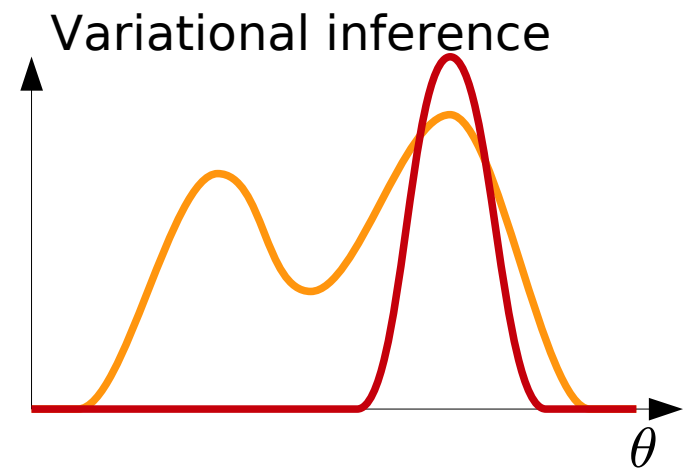
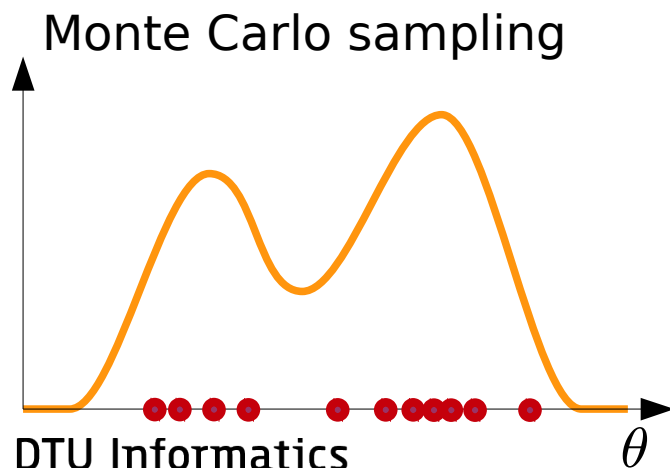
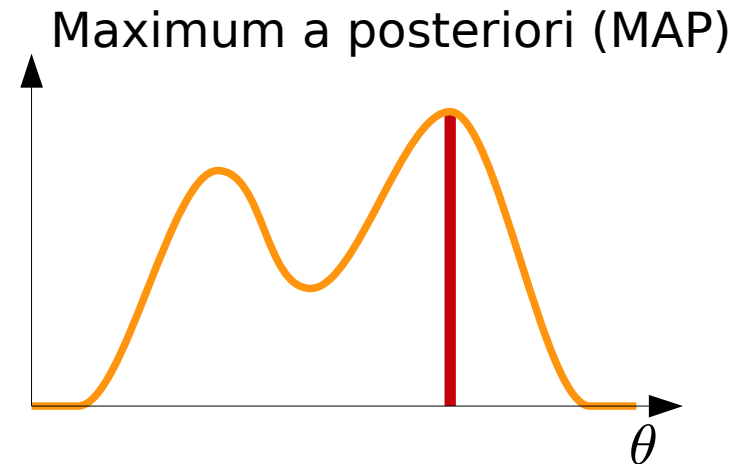
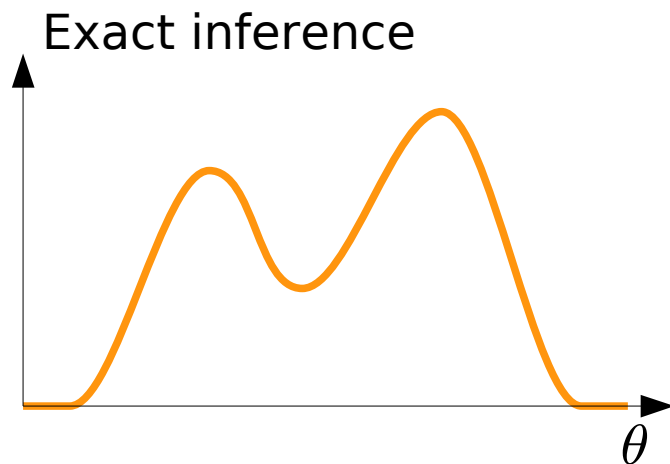
Model of data
Distribution of noise etc.

Model of factors
Non-negativity, sparsity, etc.

Model of number of components
E.g. flat (improper) distribution

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Approximate inference procedures



Infinite non-negative matrix factorization

Gibbs / Metropolis-Hastings sampling

- Sampling factorizing matrices etc.
 - Standard Gibbs sampling

$$\mathbf{W} \sim p(\mathbf{W} | \mathbf{H}, D, \mathbf{V})$$

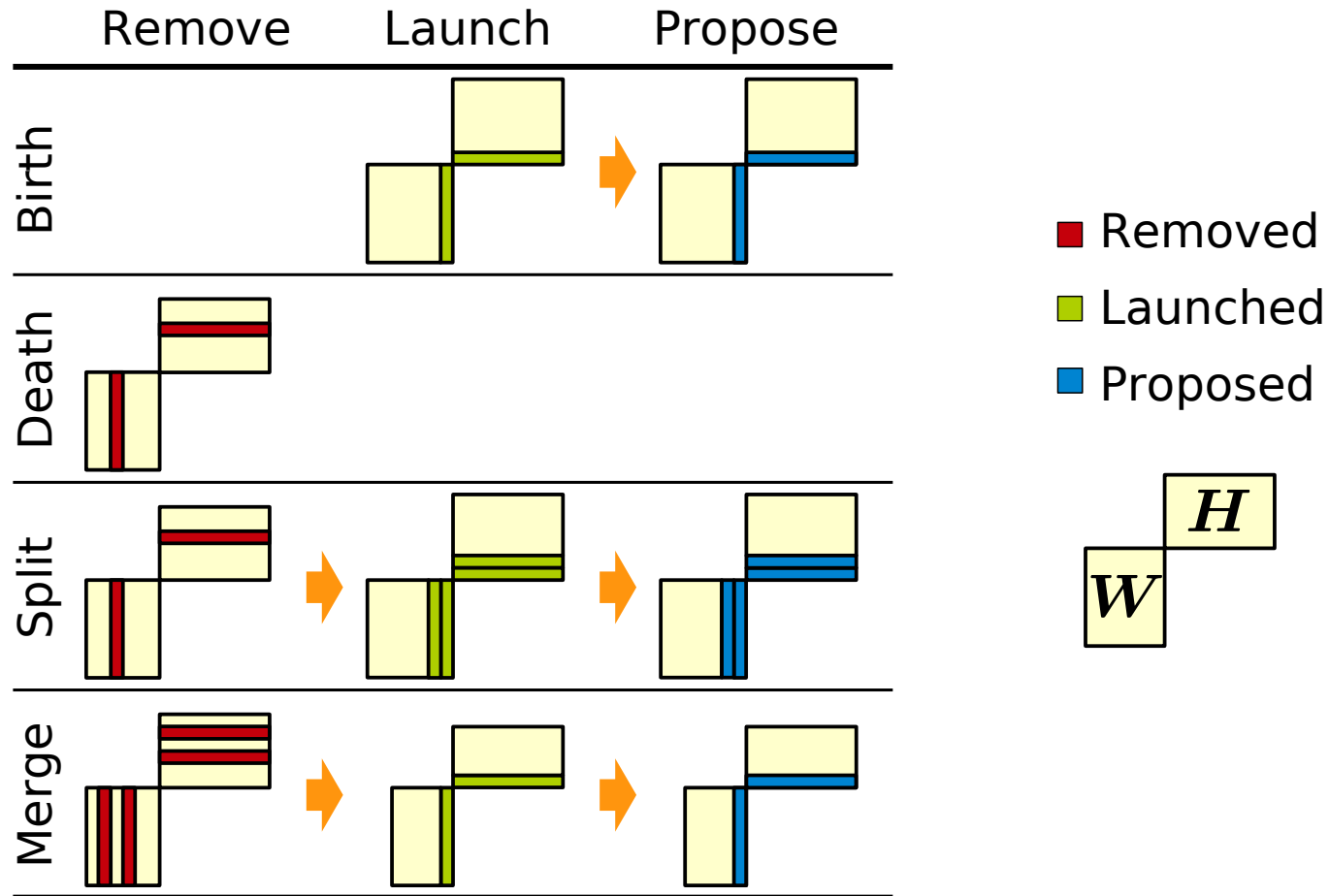
$$\mathbf{H} \sim p(\mathbf{H} | \mathbf{W}, D, \mathbf{V})$$

- Sampling the number of components
 - Requires joint update of factorizing matrices
 - Reversible jump MCMC (Metropolis-Hastings) with suitable proposal

$$\mathbf{W}^*, \mathbf{H}^*, D^* \sim q(\mathbf{W}^*, \mathbf{H}^*, D^* | \mathbf{W}, \mathbf{H}, D)$$

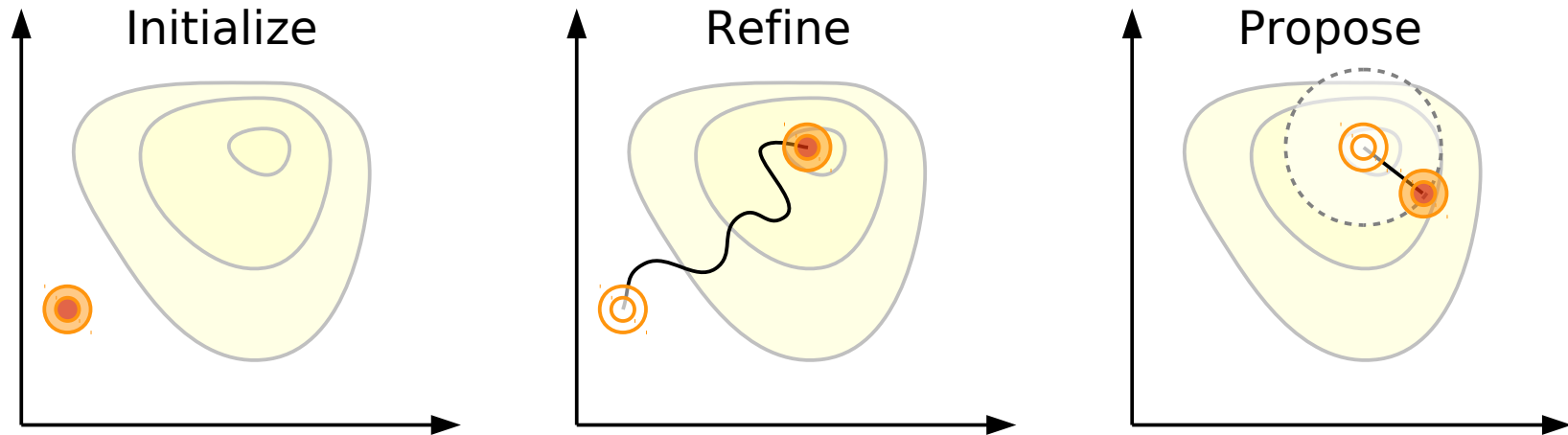
Infinite non-negative matrix factorization

Reversible jump moves



Infinite non-negative matrix factorization

Proposal based on launch state



- Initialization: Draw from prior
- Refinement: Restricted Gibbs sampling
- Proposal: One final restricted Gibbs sweep

Details and expression for acceptance rate given in the paper

Infinite non-negative matrix factorization

Summary and discussion

- Bayesian NMF with an a priori unbounded number of factors
 - Learn the number of factors from data
 - Model order selection integrated in inference
- Efficient sampling scheme for cross-dimensional jumps
 - Based on reversible jump MCMC
 - Efficient proposals through high probability launch states
- Demonstrated on real and synthetic data
 - Reliably extract the correct model order
 - Lower computational complexity than competing approaches